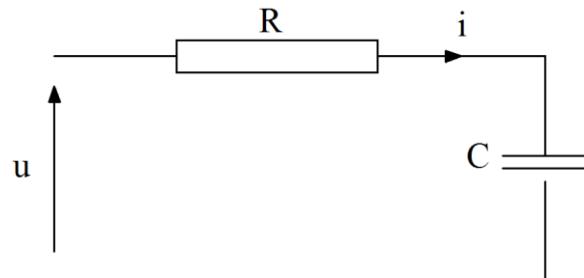


**TD 1 Automatique linéaire**  
**Au tour de la fonction de transfert**

**Exercice 1 :**



$$\begin{aligned} E_C &= \frac{1}{2} m \dot{y}^2(t) \\ E_p &= \frac{1}{2} K y^2(t) \\ \Rightarrow L &= E_C - E_p = \frac{1}{2} m \dot{y}^2(t) - \frac{1}{2} K y^2(t) \end{aligned}$$

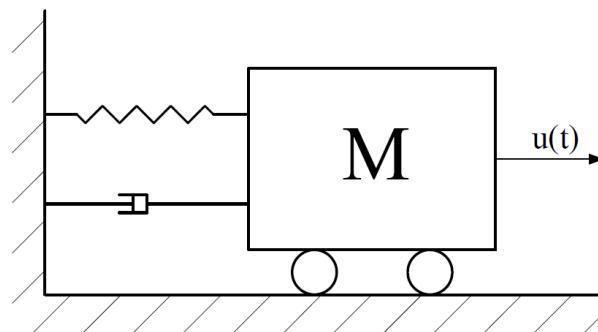
D'après Lagrange-Euler :

$$\begin{aligned} \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{y}} \right) - \frac{\partial L}{\partial y} &= - \frac{\partial D}{\partial \dot{y}} + u(t) \\ \Rightarrow m \ddot{y}(t) + k y(t) &= -\alpha \dot{y}(t) + u(t) \\ \Rightarrow m \ddot{y}(t) + \alpha \dot{y}(t) + k y(t) &= u(t) \end{aligned}$$

TL =>

$$\begin{aligned} mp^2 Y(p) + \alpha p Y(p) + KY(p) &= u(p) \\ \Rightarrow Y(p)(mp^2 + \alpha p + K) &= u(p) \\ \Rightarrow H(p) = \frac{Y(p)}{u(p)} &= \frac{1}{mp^2 + \alpha p + K} \end{aligned}$$

**Exercice 2 :**



$$\sum F_{ext} = m\vec{a}$$

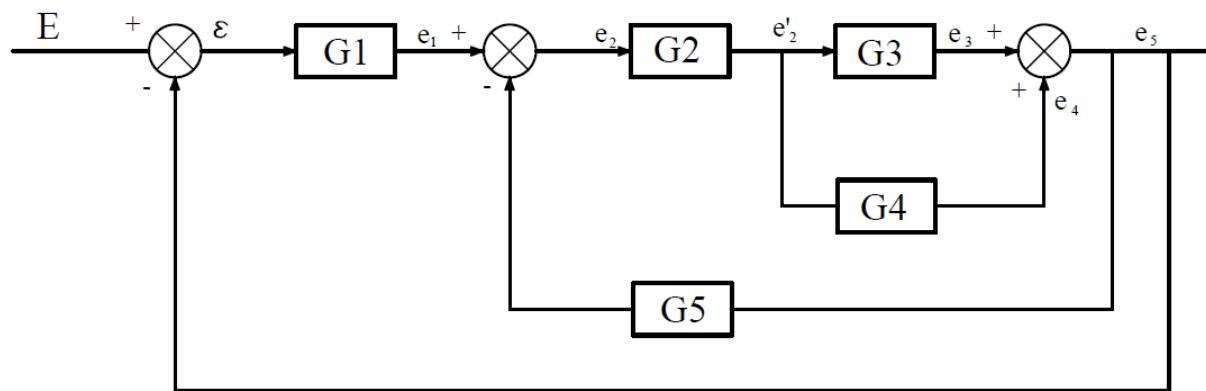
On projette sur l'axe Ox :

$$-Ky(t) - \alpha\dot{y}(t) + u(t) = m\ddot{y}(t)$$

Transformé de Laplace :

$$\begin{aligned} &\Rightarrow -KY(p) - \alpha p Y(p) + u(p) = mp^2 Y(p) \\ &\Rightarrow Y(p) \cdot (mp^2 + \alpha p + K) = u(p) \\ &\Rightarrow H(p) = \frac{Y(p)}{u(p)} = \frac{1}{mp^2 + \alpha p + K} \end{aligned}$$

### Exercice 3 :



$$\varepsilon = E - e_5$$

$$e_1 = \varepsilon \cdot G1$$

$$e_2 = e_1 - e_5 \cdot G5$$

$$e'_2 = e_2 \cdot G2$$

$$e_4 = e'_2 \cdot G4$$

$$e_3 = e'_2 \cdot G3$$

$$e_5 = e_3 + e_4$$

$$H = \frac{e_5}{E}$$

$$e_5 = e_3 + e_4 = e'_2 \cdot G3 + e'_2 \cdot G4 = e'_2 \times (G3 + G4)$$

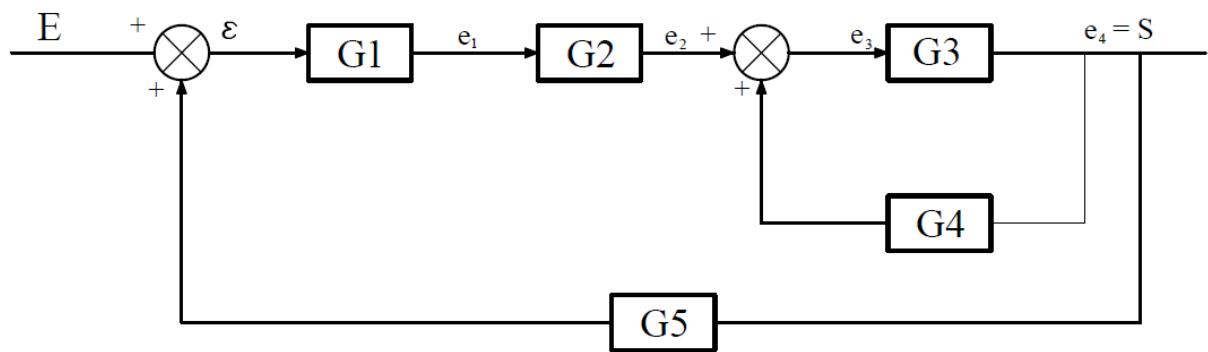
$$\Rightarrow e_5 = e_2 \cdot G2 \times (G3 + G4) = e_2 \times (G2 \cdot G3 + G2 \cdot G4)$$

$$\Rightarrow e_5 = (e_1 - e_5 \cdot G5) \times (G2 \cdot G3 + G2 \cdot G4)$$

$$\Rightarrow e_5 \times (1 + G5 \times (G2 \cdot G3 + G2 \cdot G4)) = e_1 \times (G2 \cdot G3 + G2 \cdot G4)$$

$$\begin{aligned}
 & \Rightarrow e_5 \times (1 + G5 \times (G2.G3 + G2.G4)) = \varepsilon \times (G1.G2.G3 + G1.G2.G4) \\
 & \Rightarrow e_5 \times (1 + G5 \times (G2.G3 + G2.G4)) = (E - e_5) \times (G1.G2.G3 + G1.G2.G4) \\
 & \Rightarrow e_5 \times (1 + G5 \cdot G2.(G3 + G4) + G1 \cdot G2.(G3 + G4)) = E \times G1 \cdot G2 \times (G3 + G4) \\
 & \Rightarrow e_5 = \frac{E \times G1 \times G2 \times (G3 + G4)}{1 + G5 \times G2 \times (G3 + G4) + G1 \times G2 \times (G3 + G4)} \\
 \\
 & \Rightarrow H = \frac{G1 \times G2 \times (G3 + G4)}{1 + G5 \times G2 \times (G3 + G4) + G1 \times G2 \times (G3 + G4)}
 \end{aligned}$$

#### Exercice 4 :



$$\varepsilon = E + e_4 \cdot G5$$

$$e_1 = \varepsilon \cdot G1$$

$$e_2 = e_1 \cdot G1$$

$$e_3 = e_2 + e_4 \cdot G4$$

$$e_4 = e_3 \cdot G3$$

$$H = \frac{e_4}{E}$$

$$e_4 = e_3 \cdot G3 = (e_2 + e_4 \cdot G4) \times G3$$

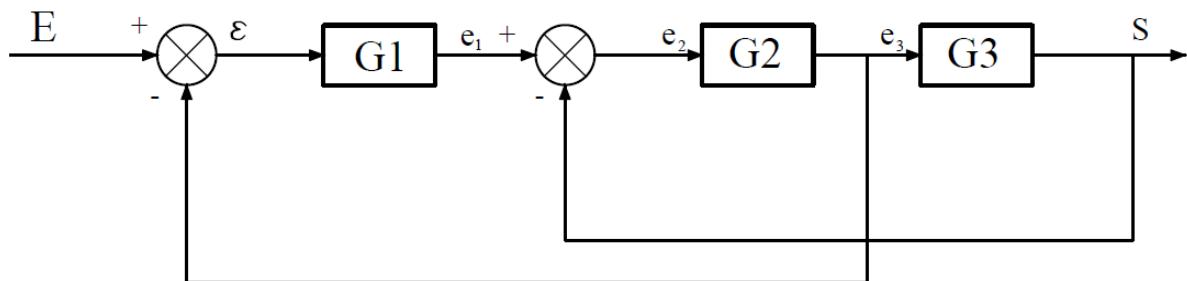
$$\Rightarrow e_4(1 - G3G4) = e_2 \cdot G3$$

$$\Rightarrow e_4(1 - G3G4) = e_1 \cdot G2G3 = \varepsilon \cdot G1 \cdot G2 \cdot G3$$

$$\Rightarrow e_4(1 - G3G4) = (E + e_4 \cdot G5) \cdot G1 \cdot G2 \cdot G3$$

$$\Rightarrow e_4 = \frac{E \cdot G1 \cdot G2 \cdot G3}{1 - G3 \cdot G4 - G1 \cdot G2 \cdot G3 \cdot G5}$$

$$\Rightarrow H = \frac{G1 \cdot G2 \cdot G3}{1 - G3 \cdot G4 - G1 \cdot G2 \cdot G3 \cdot G5}$$

**Exercice 5 :****Système 1 :**

$$S = e_3 \cdot G3$$

$$\varepsilon = E - e_3$$

$$e_3 = e_2 \cdot G2$$

$$e_2 = e_1 - S$$

$$e_1 = \varepsilon \cdot G1$$

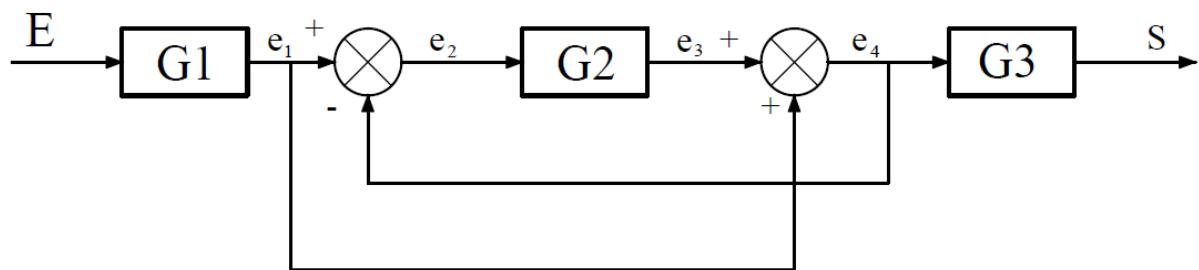
On a :

$$\begin{aligned}
 S &= e_3 \cdot G3 = e_2 \cdot G2 \cdot G3 \\
 \Rightarrow S &= e_1 \cdot G2 \cdot G3 - S \cdot G2 \cdot G3 \\
 \Rightarrow S(1 + G2 \cdot G3) &= \varepsilon \cdot G1 \cdot G2 \cdot G3 \\
 \Rightarrow S(1 + G2 \cdot G3) &= (E - e_3)G1 \cdot G2 \cdot G3 \\
 \Rightarrow S(1 + G2 \cdot G3) &= E \cdot G1 \cdot G2 \cdot G3 - e_3 \cdot G1 \cdot G2 \cdot G3 \\
 \Rightarrow S(1 + G2 \cdot G3) &= E \cdot G1 \cdot G2 \cdot G3 - \left(\frac{S}{G3}\right) \cdot G1 \cdot G2 \cdot G3 \\
 \Rightarrow S &= \frac{E \cdot G1 \cdot G2 \cdot G3}{1 + G2 \cdot G3 + G1 \cdot G2}
 \end{aligned}$$

Donc :

$$\Rightarrow H = \frac{G1 \cdot G2 \cdot G3}{1 + G2 \cdot G3 + G1 \cdot G2}$$

Système 2 :



$$S = e_4 \cdot G3$$

$$e_4 = e_1 + e_3$$

$$e_3 = e_2 \cdot G2$$

$$e_2 = e_1 - e_4$$

$$e_1 = E \cdot G1$$

On a :

$$\begin{aligned} S &= e_4 \cdot G3 = (e_1 + e_3) \times G3 = (E \cdot G1 + e_2 \cdot G2) \times G3 \\ \Rightarrow S &= E \cdot G1 \cdot G3 + e_2 \cdot G2 \cdot G3 \\ \Rightarrow S &= E \cdot G1 \cdot G3 + (e_1 - e_4) \cdot G2 \cdot G3 \\ \Rightarrow S &= E \cdot G1 \cdot G3 + e_1 \cdot G2 \cdot G3 - e_4 \cdot G2 \cdot G3 \\ \Rightarrow S &= E \cdot G1 \cdot G3 + E \cdot G1 \cdot G2 \cdot G3 - \left(\frac{S}{G3}\right) \cdot G2 \cdot G3 \\ \Rightarrow S &= \frac{E \cdot (G1 \cdot G3 + G1 \cdot G2 \cdot G3)}{1 + G2} \end{aligned}$$

Donc :

$$\Rightarrow H = \frac{G1 \cdot G3 + G1 \cdot G2 \cdot G3}{1 + G2}$$

$$E_c = \frac{1}{2} m \dot{y}^2(t)$$

$$E_p = \frac{1}{2} K y^2(t)$$

$$\Rightarrow L = E_c - E_p = \frac{1}{2} m \dot{y}^2(t) - \frac{1}{2} K y^2(t)$$

D'après Lagrange-Euler :

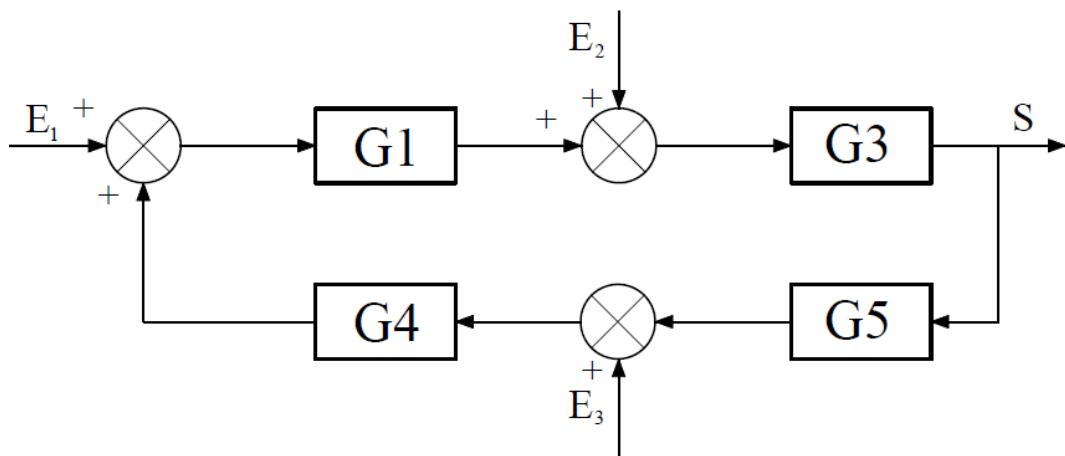
$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{y}} \right) - \frac{\partial L}{\partial y} = - \frac{\partial D}{\partial y} + u(t)$$

$$\begin{aligned}\Rightarrow m\ddot{y}(t) + ky(t) &= -\alpha\dot{y}(t) + u(t) \\ \Rightarrow m\ddot{y}(t) + \alpha\dot{y}(t) + ky(t) &= u(t)\end{aligned}$$

TL =>

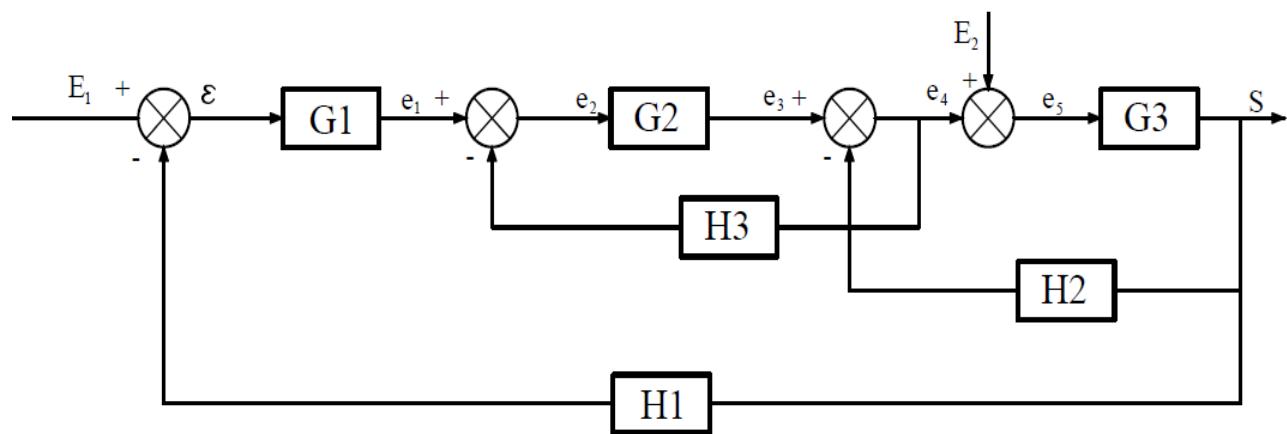
$$\begin{aligned}mp^2Y(p) + \alpha p Y(p) + KY(p) &= u(p) \\ \Rightarrow Y(p)(mp^2 + \alpha p + K) &= u(p) \\ \Rightarrow H(p) = \frac{Y(p)}{u(p)} &= \frac{1}{mp^2 + \alpha p + K}\end{aligned}$$

### Exercice 6 :



En appliquant la technique de superposition :

$$\begin{aligned}E_2 = 0 \text{ et } E_3 = 0 \quad \Rightarrow \quad H_1 &= \frac{S}{E_1} = \frac{G_1 G_3}{1 - G_1 G_3 G_4 G_5} \\ E_1 = 0 \text{ et } E_3 = 0 \quad \Rightarrow \quad H_2 &= \frac{S}{E_2} = \frac{G_3}{1 - G_1 G_3 G_4 G_5} \\ E_1 = 0 \text{ et } E_1 = 0 \quad \Rightarrow \quad H_3 &= \frac{S}{E_3} = \frac{G_5}{1 - G_1 G_3 G_4 G_5} \\ \Rightarrow H_{total} &= H_1 + H_2 + H_3 \\ \Rightarrow H_{total} &= \frac{G_3 + G_1 G_3 + G_5}{1 - G_1 G_3 G_4 G_5}\end{aligned}$$

**Exercice 7 :**

En appliquant la technique de superposition :

$$E_2 = 0 \Rightarrow H_1(p) = \frac{S}{E_1}$$

$$S = e_5 \cdot G3$$

$$\varepsilon = E1 - H1 \cdot S$$

$$e_1 = \varepsilon \cdot G1$$

$$e_2 = e_1 - H2 \cdot S$$

$$e_3 = e_2 \cdot G2$$

$$e_4 = e_3 - H2 \cdot S$$

$$e_5 = e_4$$

$$\begin{aligned}
 &\text{on a : } S = e_5 \cdot G3 = (e_3 - H2 \cdot S)G3 = (e_2 \cdot G2 - H2 \cdot S) \cdot G3 \\
 &\Rightarrow S = (e_1 \cdot G2 - e_4 \cdot G2 \cdot H3 - H2 \cdot S) \cdot G3 \\
 &\Rightarrow S = (e_1 \cdot G2 - (e_3 - H2 \cdot S) \cdot G2 \cdot H3 - H2 \cdot S) \cdot G3 \\
 &\Rightarrow S = (E1 \cdot G1 \cdot G2 - H1 \cdot S \cdot G2 \cdot G1 - (e_2 \cdot G2 - H2 \cdot S) \cdot G2 \cdot H3 - H2 \cdot S) \cdot G3 \\
 &\Rightarrow S = (E1 \cdot G1 \cdot G2 - H1 \cdot S \cdot G2 \cdot G1 - (e_3 - H2 \cdot S) \cdot G2 \cdot H3 - H2 \cdot S) \cdot G3
 \end{aligned}$$

$$\text{Or : } e_4 = e_3 - H2 \cdot S = e_5 \Rightarrow e_4 = \frac{S}{G3}$$

$$\Rightarrow e_3 = S \cdot H2 + \frac{S}{G3}$$

Donc :

$$H_1(p) = \frac{S}{E_1} = \frac{G1 \cdot G2 \cdot G3}{1 + H1 \cdot G1 \cdot G2 \cdot G3 + H3 \cdot G2 + H2 \cdot G3}$$

$$E_1 = 0 \implies H_2(p) = \frac{S}{E_2}$$

$$e_1 = S.H1.G1$$

$$e_2 = e_1 - H3.e_4$$

$$e_3 = e_2.G2$$

$$e_4 = e_3 - H2.S$$

$$e_5 = e_4 + E2$$

$$S = e_5.G3 = e_4.G3 + E2.G3 = e_3.G3 - S.H2.G3 + E2.G3$$

$$\implies S = e_2.G2.G3 - S.H2.G3 + E2.G3$$

$$\implies S = e_1.G2.G3 - e_4.H3.G2.G3 - S.H2.G3 + E2.G3$$

$$\implies S = S.H1.G1.G2.G3 - \left( \frac{S - E2.G3}{G3} \right).H3.G2.G3 - S.H2.G3 + E2.G3$$

$$\implies S = S.H1.G1.G2.G3 - (S - E2.G3).H3.G2 - S.H2.G3 + E2.G3$$

$$\implies S = \frac{E2.H3.G2.G3 + E2.G3}{1 - H1.G1.G2.G3 + H3.G2}$$

$$\implies H_2(p) = \frac{S}{E_2} = \frac{H3.G2.G3 + G3}{1 - H1.G1.G2.G3 + H3.G2}$$

Donc :

$$\implies H_{total} = H_1(p) + H_2(p)$$

$$\implies H_{total} = \frac{G1.G2.G3}{1 + H1.G1.G2.G3 + H3.G2 + H2.G3} + \frac{H3.G2.G3 + G3}{1 - H1.G1.G2.G3 + H3.G2}$$